

CECS 229 Programming Assignment #7

Due Date:

Sunday, 5/12 @ 11:59 PM

Instructions:

1. In `helpers.py`, copy-paste implementation for the following functions from your `pa6.py`:
 - `gram_schmidt()`
 - `_ref()`
 - `rank()`
2. In `structures.py`, copy-paste the implementation of the missing `Matrix` methods from `pa5.py`.
3. Complete the programming problems in the file named `pa7.py`. You may test your implementation on your Repl.it workspace by running `main.py`.
4. When you are satisfied with your implementation,
 - Submit your Repl.it workspace
 - Download the file `pa7.py` and submit it to the appropriate CodePost auto-grader folder.

Objectives:

1. Apply the QR-factorization of a matrix A to solve the system of equations $A\vec{x} = \vec{b}$.
2. Create a function that computes the determinant of an $n \times n$ `Matrix` object.
3. Use the Python built-in function `numpy.linalg.eig()` to find the eigenvalues and eigenvectors of a matrix.
4. Create a function that computes the singular value decomposition of a `Matrix` object.

Notes:

Unless otherwise stated in the FIXME comment, you may not change the outline of the algorithm provided and you may not use any built-in functions that perform the entire algorithm or replaces a part of the algorithm, unless otherwise stated.

Problem 1:

Background:

In this problem, you will implement a solver for the system of linear equations $A\vec{x} = \vec{b}$ where

- A is an $n \times n$ matrix whose columns are linearly independent

- $\vec{x} \in \mathbb{R}^n$
- $\vec{b} \in \mathbb{R}^n$

To implement the solver, you must apply the following theorem:

THM | QR-Factorization

If $A \in \mathbb{F}^{m \times n}$ matrix with linearly independent columns $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n$, then there exists,

1. an $m \times n$ matrix Q whose columns $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ are orthonormal, and
2. an $n \times n$ matrix R that is upper triangular and whose entries are defined by,

$$r_{ij} = \begin{cases} \langle \vec{u}_i, \vec{a}_j \rangle & \text{for } i \leq j \\ 0 & \text{for } i > j \end{cases}$$

such that $A = QR$. This referred to as the QR factorization (or decomposition) of matrix A .

To find matrices Q and R from the QR Factorization Theorem, we apply Gram-Schmidt process to the columns of A . Then,

- the columns of Q will be the orthonormal vectors $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$ returned by the Gram Schimdt process, and
- the entries r_{ij} of R will be computed using each column \vec{u}_i as defined in the theorem.

Your Task:

Assuming $A \in \mathbb{R}^{n \times n}$ is a `Matrix` object, and $\vec{b} \in \mathbb{R}^n$ is a `Vec` object, finish the implementation of the function `qr_solve(A, b)` which uses the QR-factorization of A to compute and return the solution to the system $A\vec{x} = \vec{b}$.

- INPUT:
 - `A` : `Matrix` object
 - `b` : `Vec` object
- OUTPUT:
 - `Vec` object representing the solution to the system $A\vec{x} = \vec{b}$.

HINT:

If $A = QR$, then $A\vec{x} = \vec{b}$ becomes $QR\vec{x} = \vec{b}$. What happens if we multiply both sides of the equation by the transpose of Q ? i.e., What does $Q^tQR\vec{x} = Q^t\vec{b}$ simplify to?

```
In [ ]: def qr_solve(A : Matrix, b: Vec):
        """
        Solves the system of equations Ax = b by using the
        QR factorization of Matrix A
        :param A: Matrix of coefficients of the system
        :param b: Vec of constants
        :return: Vec solution to the system
```

```

"""
# Constructing U
# U should be the set of orthonormal vectors returned
# by applying Gram-Schmidt Process to the columns of A
U = None # FIXME: Replace with the appropriate line
n = len(U)

# Constructing Q
# Q should be the matrix whose columns are the elements
# of the vector in set U
Q = Matrix([[None for j in range(n)] for i in range(n)])
for j in range(n):
    pass # FIXME: Replace with the appropriate line

# Constructing R
R = Matrix([[0 for j in range(n)] for i in range(n)])
for j in range(n):
    for i in range(n):
        if i <= j:
            pass # FIXME: Replace with the appropriate line

# Constructing the solution vector x
b_star = Q.transpose() * b
x = [None for i in range(n)]
# FIXME: find the components of the solution vector
#         and replace them into elements of x
return Vec(x)

```

Problem 2:

Implement the helper function `_submatrix(A, i, j)` which creates and returns the sub-matrix that results from omitting row i -th row and j column of `A`.

- INPUT:
 - `A`: `Matrix` object representing an $m \times n$ matrix
 - `i`: int index of a row of `A` satisfying $1 \leq i \leq m$
 - `j`: int index of a column of `A` satisfying $1 \leq j \leq n$
- OUTPUT:
 - `Matrix` object of the sub-matrix

```

In [ ]: def _submatrix(A : Matrix, i : int, j: int):
        """
        constructs the sub-matrix of an mxn Matrix A that
        results from omitting the i-th row and j-th column;
        i and j satisfy that 0 <= i <= m, and 0 <= j <= n
        :param A: Matrix object
        :param i: int index of row to omit
        :param j: int index of column to omit
        :return: Matrix object representing the sub-matrix
        """
        m, n = A.dim()
        pass # FIXME: Implement this function

```

Problem 3:

Finish the implementation of the function `determinant(A)` which computes the determinant of $n \times n$ matrix `A`.

- INPUT:
 - `A`: `Matrix` object
- OUTPUT:
 - the determinant as a `float` value

```
In [ ]: def determinant(A: Matrix):
        """
        computes the determinant of square Matrix A;
        Raises ValueError if A is not a square matrix.
        :param A: Matrix object
        :return: float value of determinant
        """
        m, n = A.dim()
        if m != n:
            raise ValueError(f"Determinant is not defined for Matrix with dimension {m}x{n}")
        if n == 1:
            return None # FIXME: Return the correct value
        elif n == 2:
            return None # FIXME: Return the correct value
        else:
            d = 0
            # FIXME: Update d so that it holds the determinant
            #         of the matrix. HINT: You should apply a
            #         recursive call to determinant()
            return d
```

Problem 4:

Implement the function `eigen_wrapper(A)` which uses Python built-in function `numpy.linalg.eig()` to create a dictionary with eigenvalues of `Matrix A` as keys, and their corresponding list of eigenvectors as values.

- INPUT:
 - `A`: `Matrix` object
- OUTPUT:
 - Python dictionary

```
In [ ]: def eigen_wrapper(A: Matrix):
        """
        uses numpy.linalg.eig() to create a dictionary with
        eigenvalues of Matrix A as keys, and their corresponding
        list of eigenvectors as values.
        :param A: Matrix object
        :return: Python dictionary
```

```
"""
pass # FIXME: Implement this function
```

Problem 5:

Finish the implementation of function `svd(A)` so that it returns the singular value decomposition of A . Recall that the singular value decomposition of a matrix $A \in \mathbb{R}^{m \times n}$ consists of matrices,

- $\Sigma \in \mathbb{R}^{m \times n}$: a diagonal matrix whose main diagonal hold the singular values of $A^T A$ in decreasing order,

$$\begin{bmatrix} \sigma_1 & 0 & 0 & \cdots & 0 \\ 0 & \sigma_2 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & \sigma_r & 0 \\ 0 & \cdots & \cdots & \cdots & 0 \end{bmatrix}$$

i.e., $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_r$ where $r = \text{number of eigenvalues of } A^T A$

- $V \in \mathbb{R}^{n \times n}$: the matrix whose columns are the eigenvectors of $A^T A$. The order of the columns corresponds to the order of the singular values, i.e. the first column is the eigenvector corresponding to the largest singular value σ_1 , the second column is the eigenvector correspond to σ_2 , etc.
- $U \in \mathbb{R}^{m \times m}$: the matrix whose columns are given by $\vec{u}_j = \frac{1}{\sigma_j} A \vec{v}_j$

- INPUT:
 - `A`: Matrix object
- OUTPUT:
 - tuple with Matrix objects `(U, Sigma, V)`

```
In [ ]: # ----- PROBLEM 5 ----- #
def svd(A: Matrix):
    """
    computes the singular value decomposition of Matrix A;
    returns Matrix objects U, Sigma, and V such that
        1. V is the Matrix whose columns are eigenvectors of
           A.transpose() * A
        2. Sigma is a diagonal Matrix of singular values of
           A.transpose() * A appearing in descending order along
           the main diagonal
        3. U is the Matrix whose j-th column u_j satisfies
           A * v_j = sigma_j * u_j where sigma_j is the j-th singular value in
           decreasing order and v_j is the j-th column vector of V
        4. A = U * Sigma * V.transpose()
    :param A: Matrix object
```

```

        :return: tuple with Matrix objects; (U, Sigma, V)
    """
    m, n = A.dim()
    aTa = A.transpose() * A
    eigen = eigen_wrapper(aTa)
    eigenvalues = np.sort_complex(list(eigen.keys())).tolist()[::-1]

    # Constructing V
    # V should be the mxm matrix whose columns
    # are the eigenvectors of matrix A.transpose() * A
    V = Matrix([[None for j in range(n)] for i in range(n)])
    for j in range(1, n + 1):
        pass # FIXME: Replace this with the lines that will
            # correctly build the entries of V

    # Constructing Sigma
    # Sigma should be the mxn matrix of singular values.
    singular_values = None # FIXME: Replace this so that singular_values
    # holds a list of singular values of A
    # in decreasing order
    Sigma = Matrix([[0 for j in range(n)] for i in range(m)])
    for i in range(1, m + 1):
        pass # FIXME: Replace this with the lines that will correctly
            # build the entries of Sigma

    # Constructing U
    # U should be the matrix whose j-th column is given by
    # A * vj / sj where vj is the j-th eigenvector of A.transpose() * A
    # and sj is the corresponding j-th singular value
    U = Matrix([[None for j in range(m)] for i in range(m)])
    for j in range(1, m + 1):
        pass # FIXME: Replace this with the lines that will
            # correctly build the entries of U
    return (U, Sigma, V)

```